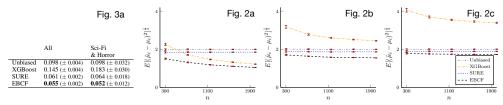
**Referee 1:** We thank the referee for thoughtful feedback. We will further emphasize in the introduction that the 1 considered problem of estimating means with contextual side information is ubiquitous in real-world settings. In 2 high-throughput *biological studies* it is important to estimate effect sizes for genes based on extremely small samples 3 (e.g. 3 patients with cancer vs. 3 healthy) and there exists a rich annotation and categorization of genes to be used as 4 covariates. In the surveying of subpopulations (e.g. by the US Census Bureau) one can improve noisy estimates (e.g. 5 on average income) for small communities by using geographical and economic covariates. In *baseball statistics*, our 6 7 methods can be used to improve estimation of the batting average of each player, say to predict their performance in the second half of a season from the first, and covariate information could include salary, team and previous performance. 8 We chose the MovieLens dataset because it is familiar to the NeurIPS community and illustrates our main statistical 9 considerations; we do not argue for the use of EBCF in Recommender systems. By the same token, however, typical 10 Recommender systems are not good at predicting average ratings for sparsely watched items. Say a user comes across 11 a movie on their own, then an improved rating estimate could help them choose whether to watch that movie or not. 12 Furthermore, improved rating estimators could be useful to rank, say, new indie movies based on few initial ratings. 13

As suggested by the referee we have added confidence intervals (CI) for all empirical results (see plot below). For Fig.3 we report standard CIs of half-width  $2 \times s.e.$  (standard error), for Fig.2 the error bars are inflated to  $10 \times s.e.$ ,

since otherwise they would not be visible at all.



17 We have also analyzed an additional real world dataset, the Communities and Crimes unnormalized dataset from the

<sup>18</sup> UCI repository. Our task is to predict the nonviolent crime rate per 1k population for each community. We make the <sup>19</sup> problem harder by using hypergeometric sampling to subsample the population of each community to  $B \in \{200, 500\}$ .

The mean squared errors and 95% CIs are as follows for B = 200: Unbiased  $224(\pm 16)$ , XGBoost  $168(\pm 20)$ , SURE

 $_{21}$  184(±19) and EBCF 149(±20). For B = 500 they are: Unbiased 92(±8), XGBoost 122(±15), SURE 86(±8) and

EBCF  $80(\pm 9)$ . The revised manuscript will contain the details of this analysis and additional simulation results.

**Referee 2:** We thank the referee for the feedback. EBCF is the proposed method and stands for Empirical Bayes with Cross-Fitting; we will further clarify in the text. Furthermore, we have added standard errors (see reply to Referee 1).

Referee 3: We want to clarify that our results are not just "standard linear/nonparametric regression" and allowing 25 A > 0 is crucial to our method. Only in the case A = 0 do our results collapse to standard regression. Let us note some 26 differences (which we will further clarify in the manuscript): First, our objective is to estimate the  $\mu_i$  with small mean 27 squared error (MSE), not the regression function  $m(\cdot)$ . Second, for A > 0 the MSE for estimating  $\mu_i$  is strictly > 0 and 28 cannot go down to 0 even as  $n \to \infty$ . In standard regression treatments the error does go to 0. Instead, in our minimax 29 analysis we consider the difference between the mean squared error and the Bayes risk (the regret): We then proceed to 30 show that when the covariates and  $m(\cdot)$  satisfy classical regression assumptions (e.g. bounded  $X_i$  and Lipschitz  $m(\cdot)$ ), 31 then the regret in estimating  $\mu_i$  is precisely characterized by the familiar minimax rates for nonparametric regression. 32 This result is *not* a trivial consequence of existing results in nonparametrics; it is instead one of our contributions 33 through Lemma 1 and Theorem 2. 34

On the other hand, we agree with the referee that e.g. bounded  $X_i$  seems restrictive. This is why we then tackle the problem of robustness to misspecification in Section 4. Here our results are novel even under the pure regression setting (i.e. A = 0). Theorem 6 holds under no assumptions on  $\hat{m}(\cdot)$  (it could be a deep neural net or a k-NN regressor or ...), nor on  $m(\cdot)$  nor on the support of  $X_i$ . Prop. 7 also makes no assumptions on the support of  $X_i$ .

Finally, we thank the referee for an excellent suggestion on strengthening our results; we present a simplified sketch here: Consider the setup of the paper with *n* observations  $Z_i$  with variance  $\sigma^2$ , but now the n + 1-th observation has variance  $\tau^2$  which may be  $\neq \sigma^2$ . Then in the Lipschitz case, extending Theorem 4, we can prove a regret that scales as  $MSE - \frac{A\tau^2}{A+\tau^2} \sim \frac{\tau}{A+\tau^2} (\frac{A+\sigma^2}{n})^{2/3}$  (note that  $A\tau^2/(A+\tau^2)$  is the Bayes risk). Letting  $\tau^2 \sim 1/N$  and rearranging, similar to the referee's insight, we get  $MSE^{1/2} \sim N^{-1/2} + N^{-1}n^{-1/3}$ . The rapid decay of the 2nd term in N theoretically and quantitatively verifies our empirical results (e.g. Figs 2b,c): The quality of the regression fit is important only for small N where we benefit most from empirical Bayes shrinkage, while for large N it does not matter.

**Referee 4:** We thank the referee for the kind words and a very detailed summary of our contributions. One shortcoming of the method is that the covariates  $X_i$  can modulate the effect size distribution only through the map  $X_i \mapsto \mathcal{N}(m(X_i), A)$ . We have comprehensively studied this case in the paper, however in future work we hope to explore additional effect modifications, for example  $X_i \mapsto \mathcal{N}(0, A(X_i))$  could be more relevant for differential gene expression studies in biology. Heavy-tailed priors and priors with a point mass at 0 are also of interest.