We thank the reviewers for the insightful and constructive comments. In what follows, we provide our response to the 1

major concerns raised. 2

**Reviewer 1:** We agree with the presentation and reference issues raised, and will revise the paper as advised. 3

**Reviewer 2, Comments 1 & 2:** We agree that  $\log^*(n)$  is a small number and further reducing it is not interesting. 4 However, we note that our focus is not to reduce the round number below  $\log^*(n)$ , but to achieve  $O(\log^*(n))$  rounds 5 without relying on the unrealistic assumptions made in [4]. In particular, [4] assumes that  $\Delta_k$  (i.e., the difference 6 between the means of the  $k^{th}$  and  $(k+1)^{th}$  largest arms) is known, which is seldom the case in practice given that 7 the means of all arms are unknown in advance. In contrast, our algorithms do not require any prior knowledge of  $\Delta_k$ ; 8 we allow users to choose an error parameter  $\epsilon \in (0,1)$  to strike a trade-off between accuracy and efficiency. In our 9 submission, we discuss the above issues in Lines 80-88 and 103-106. We also note that our  $O(\log_{\frac{k}{2}}^{*}(n))$  result does not 10 contradict the  $\Omega(\log^*(n))$  lower bound in [4], since the latter regard k and  $\delta$  as constants, whereas we consider them to 11 be variables. If we also consider k and  $\delta$  to be constants, then our result would match the lower bound in [4]. 12 **Reviewer 2, Comment 3:** We will explicitly define  $\log_{h}^{*}(n)$  as advised. 13

**Reviewer 2, Comment 4:** We have considered the suggested approach (which tests  $\Delta = 1, \gamma, \gamma^2, \cdots$ ), but found that its complexity is inferior to ours, as explained in the following. Assume that the approach stops testing when  $\Delta = \gamma^{2t}$ . For the PAC setting (see Problem 1 in our submission), since  $\gamma^{2t} < \Delta_k$ , the suggest approach has to call the algorithm in [4]  $O(\log \Delta_k^{-1})$  times, each of which requires  $\log^*(n)$  rounds. Therefore, its round complexity is 14 15 16 17  $O(\log \Delta_k^{-1} \cdot \log^* n)$ , which is inferior to our  $O(\log_{\frac{k}{k}}^*(n))$  result. For the exact top-k setting (see Problem 3 in our 18 submission), let us consider a bandit instance where we have (i) k arms with means  $\theta$ , (ii) n - k arms with means  $\theta - \Delta_k$ , and  $\gamma^t = 2\Delta_k$  (i.e.,  $\gamma^{2t} = 4\Delta_k^2$ ). If the suggested approach stops testing at  $\Delta = \gamma^{2t}$ , its query complexity is 19 20 at least  $O\left(\frac{n}{\Delta_k^4}\log\frac{k}{\delta}\right)$ , which is inferior to our query complexity  $O\left(\frac{n}{\Delta_k^2}\log\frac{k \cdot \log \Delta_k^{-1}}{\delta}\right)$ . 21

**Reviewer 3, Comment 1:** For the proof of Lemma 1, we note that  $\hat{\theta}_{i^*} \ge \theta_i^* - \epsilon/8$  holds with high probability even at the very beginning. In particular, in the first iteration (i.e., r = 1),  $S_r$  is exactly the same as the input arm set S (i.e., 22 23

24

 $S_1 = S$ ), and Algorithm 1 samples at least  $\frac{32}{\epsilon^2} \log \frac{k}{\delta_1}$  times for every arm in  $S_1$ . Therefore, every arm  $i^*$  is initialized for  $\hat{\theta}_{i^*}$ . Based on Hoeffding bound, we have  $\hat{\theta}_{i^*} \ge \hat{\theta}_i^* - \epsilon/8$  with probability at least  $1 - \frac{\delta_1}{k}$ , for the case of r = 1. 25

The case for r > 1 follow from an induction on r, as shown in Lines 362-377 in our supplementary material. 26

Specifically, suppose that  $\hat{\theta}_{i^*} \ge \theta_i^* - \epsilon/8$  holds in the (r-1)-th iteration. If  $\hat{\theta}_{i^*}$  is NOT updated in the r-th iteration, 27

then  $\hat{\theta}_{i^*} \ge \theta_i^* - \epsilon/8$  remains. Meanwhile, if  $\hat{\theta}_{i^*}$  is updated in the r-th iteration, then we can apply the Hoeffding bound 28

to show that after the update,  $\hat{\theta}_{i^*} \ge \theta_i^* - \epsilon/8$  holds with at least  $1 - \frac{\delta_r}{k}$  probability. By the union bound, the probability 29

that  $\hat{\theta}_{i^*} \ge \theta_i^* - \epsilon/8$  holds in all iterations is at least  $1 - \frac{\delta}{2k}$  (see Eq. (7) in our supplementary material). 30

We will revise the proof of Lemma 1 to avoid confusions over the cases of (i) r = 1 and (ii) r > 1 and  $\hat{\theta}_{i*}$  is not updated 31 in the *r*-th iteration. 32

**Reviewer 3, Comment 2:** Regarding the comparison between  $\delta E$  and other fixed confidence BAI algorithms: we have 33 actually done such a comparison in our submission (see Figures 1 and 2). In particular, we compare  $\delta E$  and  $k \cdot \delta E$ 34 against ME [5] and ME-AS [6], both of which are state-of-the-art methods for fixed confidence instance-independent 35 BAI. Our results demonstrate that  $\delta E$  (resp. k- $\delta E$ ) significantly outperforms ME (resp. ME-AS) in terms of query cost. 36 In addition, in Section 4.2, we use  $\delta E$  as a subroutine to construct an algorithm (referred to as EG- $\delta E$ ) for exact (instead 37 of PAC) top-k arm identification, and we show that it outperforms the state-of-the-art elimination-based method [8] and 38 UCB-based method [17]. 39

Meanwhile, for  $\delta ER$ , we find it difficult to compare it with fixed budget BAI algorithms, due to the significant difference 40 in the number of rounds that they require. Specifically, existing fixed budget BAI algorithms (e.g., [8]) require at least 41

 $\log(n)$  rounds, whereas  $\delta ER$  requires at most  $\log^*(n)$  rounds. This makes it difficult to identify a setting of round 42 numbers to conduct a fair comparison of the algorithms. 43

**Reviewer 3.** Comments 3 & 4: We will clarify the motivation for multiple testing and detail the Exponential-Gap-44 Elimination algorithm as advised. 45