

# NIPS Demo Session

corridor

**Visualizing NIPS  
Cooperations using  
Multiple Maps t-SNE**

Laurens van der Maaten

1b

**Real-time Topology  
Learning**

Kynan Eng

2b

**Infer.NET: Software for  
Graphical Models**

Tom Minka

3b

5b

**The Chiara: A New  
Robotic Platform for  
Education and Research**

David S Touretzky

4b

**RL-Glue: From Grid  
Worlds to Sensor Rich  
Robots**

Brian Tanner

6b

**Machine Perception for  
Human Machine  
Interaction**  
Paul L Ruvolo