

corridor

# NIPS Demo Session

CLOP: a Matlab  
learning object  
package

Guyon Isabelle  
Clopinet

1b

Adaptive Bottle

Adiloglu Kamil  
Berlin University of  
Technology

2b

Holistic Scene Understanding from Visual and  
Range Data

Gould Stephen  
Stanford University

5b

4b

Robust Biped  
Locomotion  
Using Simple  
Low-  
dimensional  
Control Policies

van de Panne  
Michiel

8b

Visualization of depth/  
motion perception by model  
cortical neurons  
Tsang Eric Kong-Chau  
Hong Kong  
University of Science and  
Technology

7b

Basal-ganglia-inspired  
hierarchical reinforcement  
learning in an AIBO robot

Hearn Robert  
Dartmouth

6b

Tekkotsu Cognitive  
Robotics

Touretzky David  
Carnegie Mellon